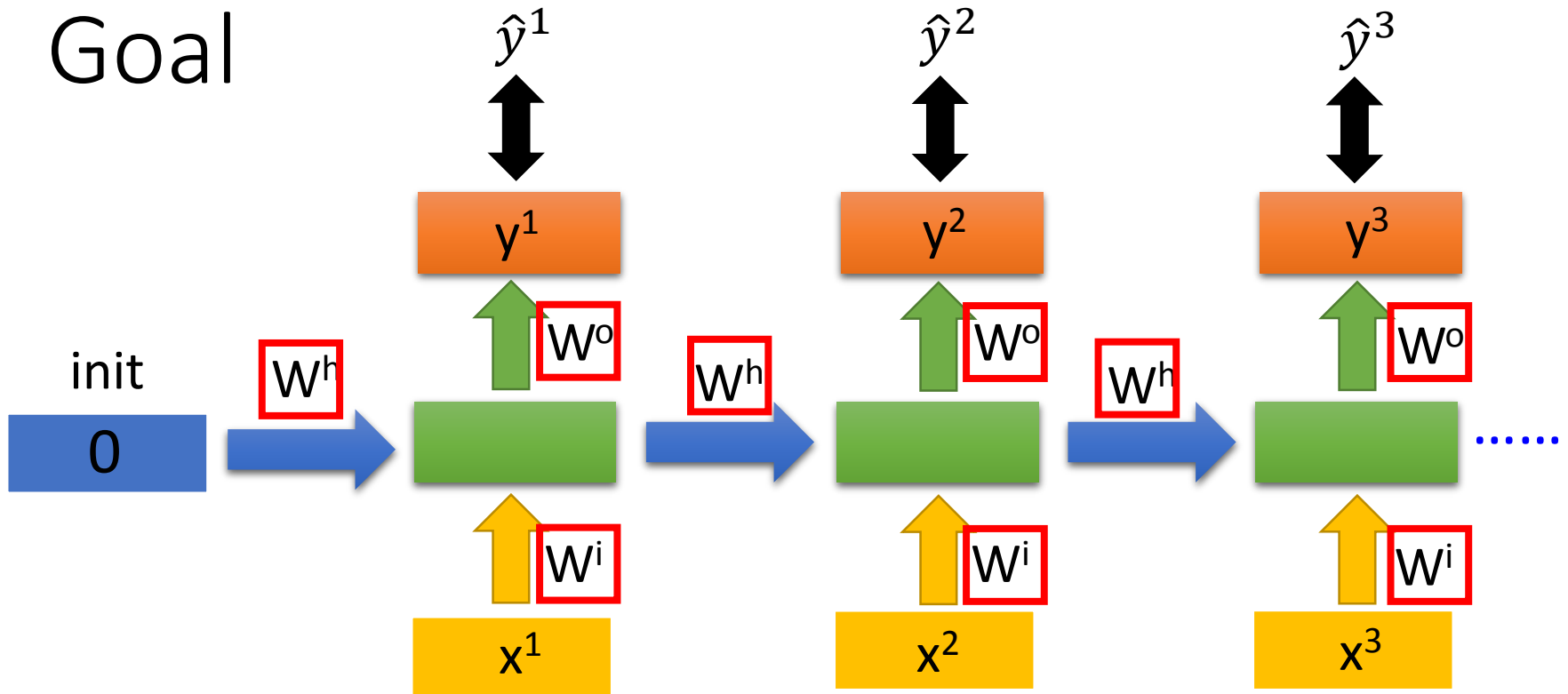


Training Recurrent Neural Network

Hung-yi Lee

Goal



$$C = \frac{1}{2} \sum_{n=1}^N \|y^n - \hat{y}^n\|^2$$

$$C^n = \|y^n - \hat{y}^n\|^2$$

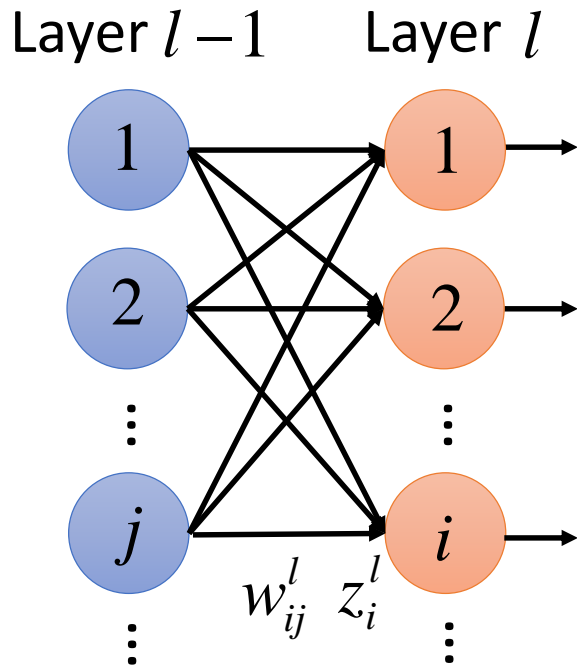
All element w in W^h , W^i or W^o

$$\blackrightarrow w \leftarrow w - \eta \partial C^n / \partial w$$

Backpropagation through time (BPTT)

Review: Backpropagation

$$\frac{\partial C_x}{\partial w_{ij}^l} = \frac{\partial z_i^l}{\partial w_{ij}^l} \frac{\partial C_x}{\partial z_i^l}$$



$$\begin{cases} a_j^{l-1} & l > 1 \\ x_j & l = 1 \end{cases}$$

Forward Pass

$$z^1 = W^1 x + b^1$$

$$a^1 = \sigma(z^1)$$

.....

$$z^{l-1} = W^{l-1} a^{l-2} + b^{l-1}$$

$$a^{l-1} = \sigma(z^{l-1})$$

Error signal

$$\delta_i^l$$

Backward Pass

$$\delta^L = \sigma'(z^L) \bullet \nabla C_x(y)$$

$$\delta^{L-1} = \sigma'(z^{L-1}) \bullet (W^L)^T \delta^L$$

.....

$$\delta^l = \sigma'(z^l) \bullet (W^{l+1})^T \delta^{l+1}$$

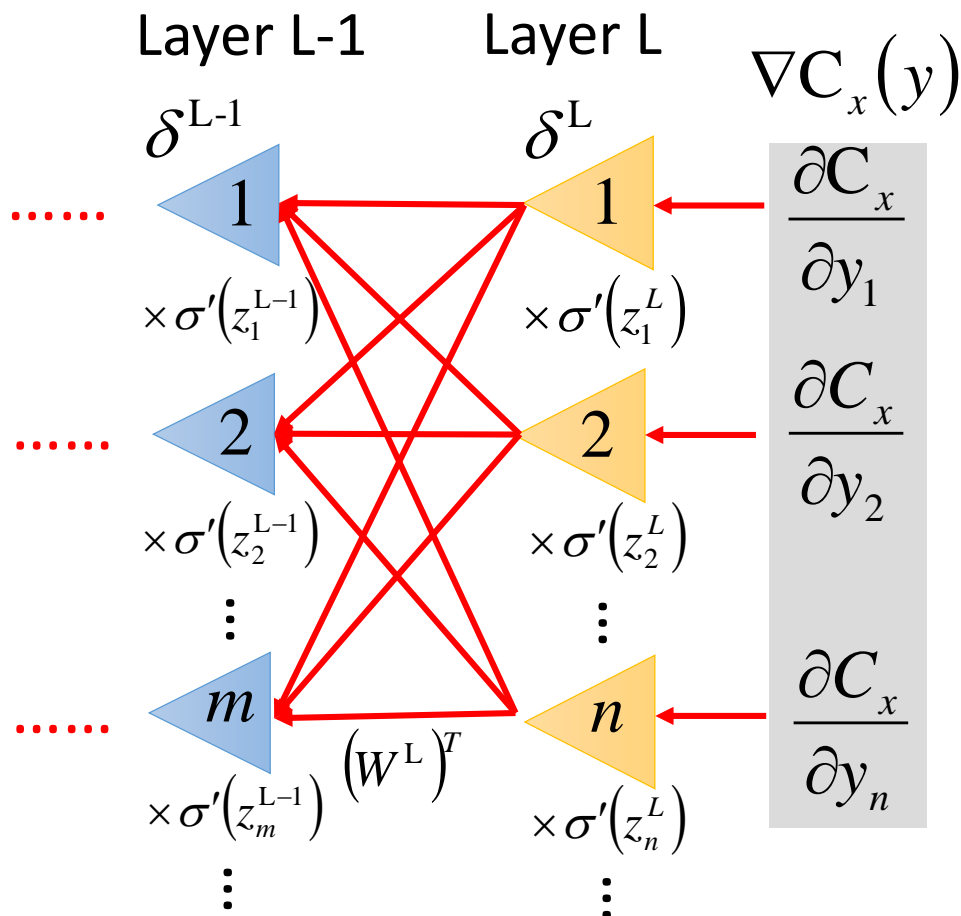
.....

Review: Backpropagation

$$\frac{\partial C_x}{\partial w_{ij}^l} = \frac{\partial z_i^l}{\partial w_{ij}^l} \frac{\partial C_x}{\partial z_i^l}$$

Error signal

$$\delta_i^l$$



Backward Pass

$$\delta^L = \sigma'(z^L) \bullet \nabla C_x(y)$$

$$\delta^{L-1} = \sigma'(z^{L-1}) \bullet (W^L)^T \delta^L$$

.....

$$\delta^l = \sigma'(z^l) \bullet (W^{l+1})^T \delta^{l+1}$$

.....

Backpropagation through Time

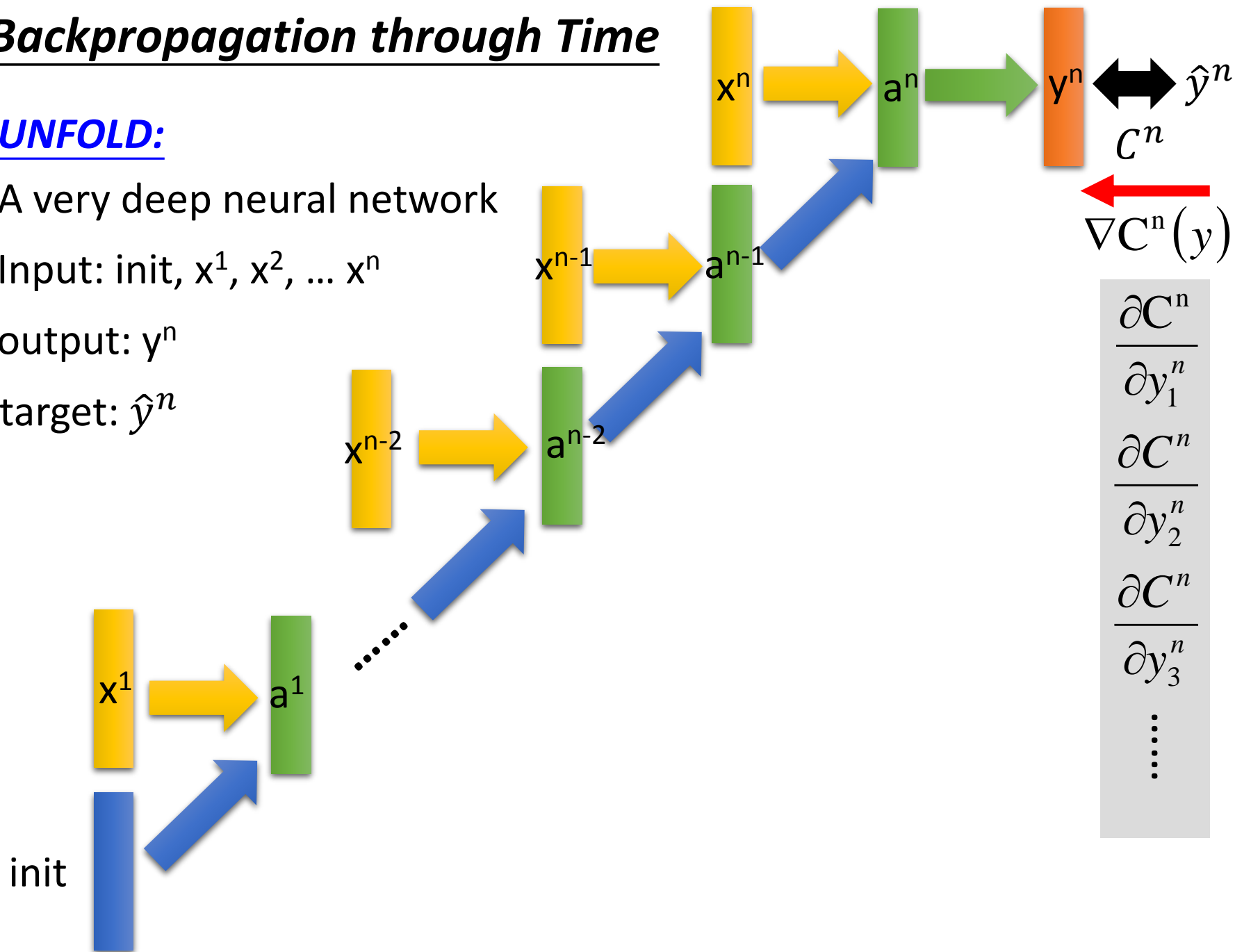
UNFOLD:

A very deep neural network

Input: init, x^1, x^2, \dots, x^n

output: y^n

target: \hat{y}^n



Backpropagation through Time

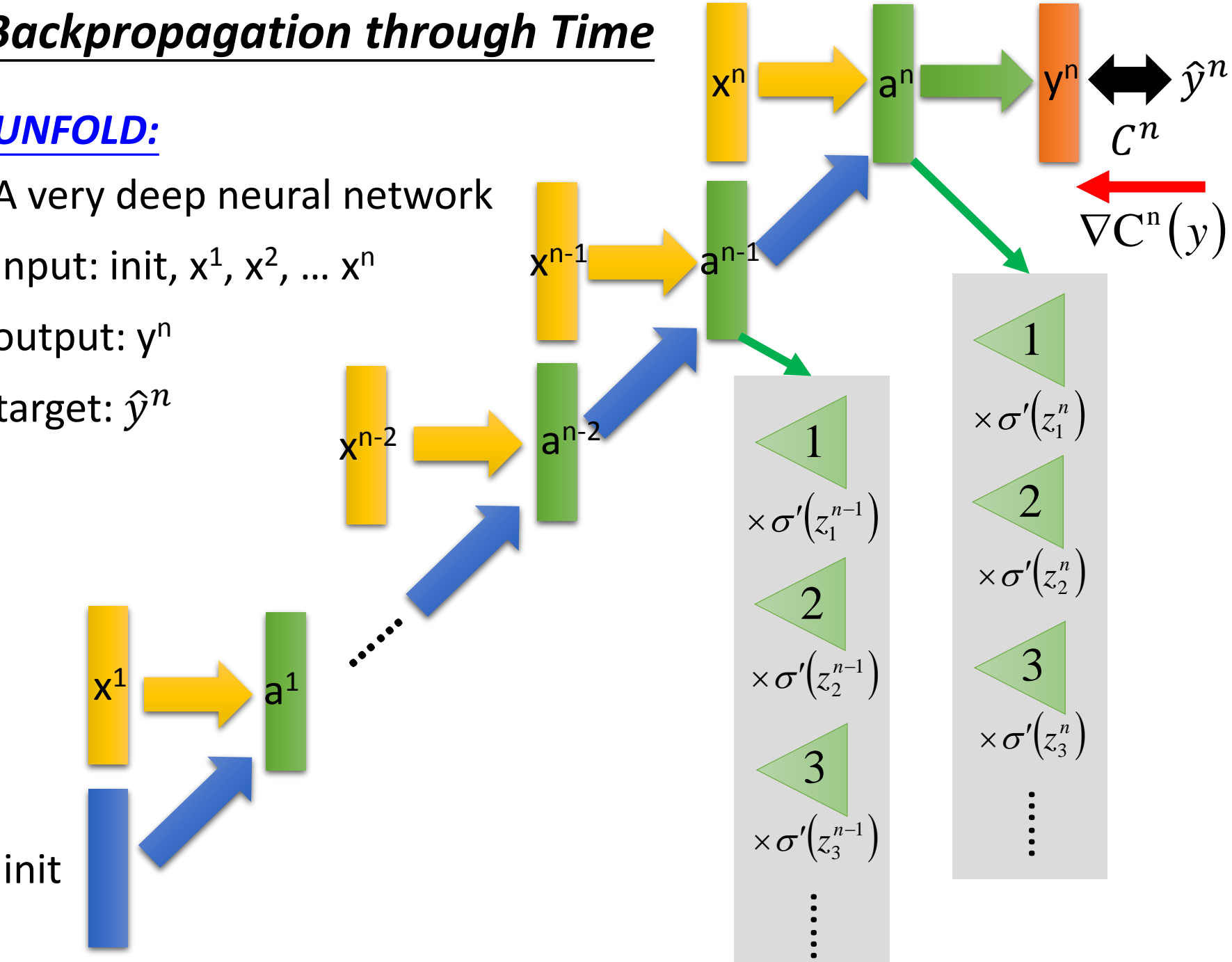
UNFOLD:

A very deep neural network

Input: init, x^1, x^2, \dots, x^n

output: y^n

target: \hat{y}^n



Backpropagation through Time

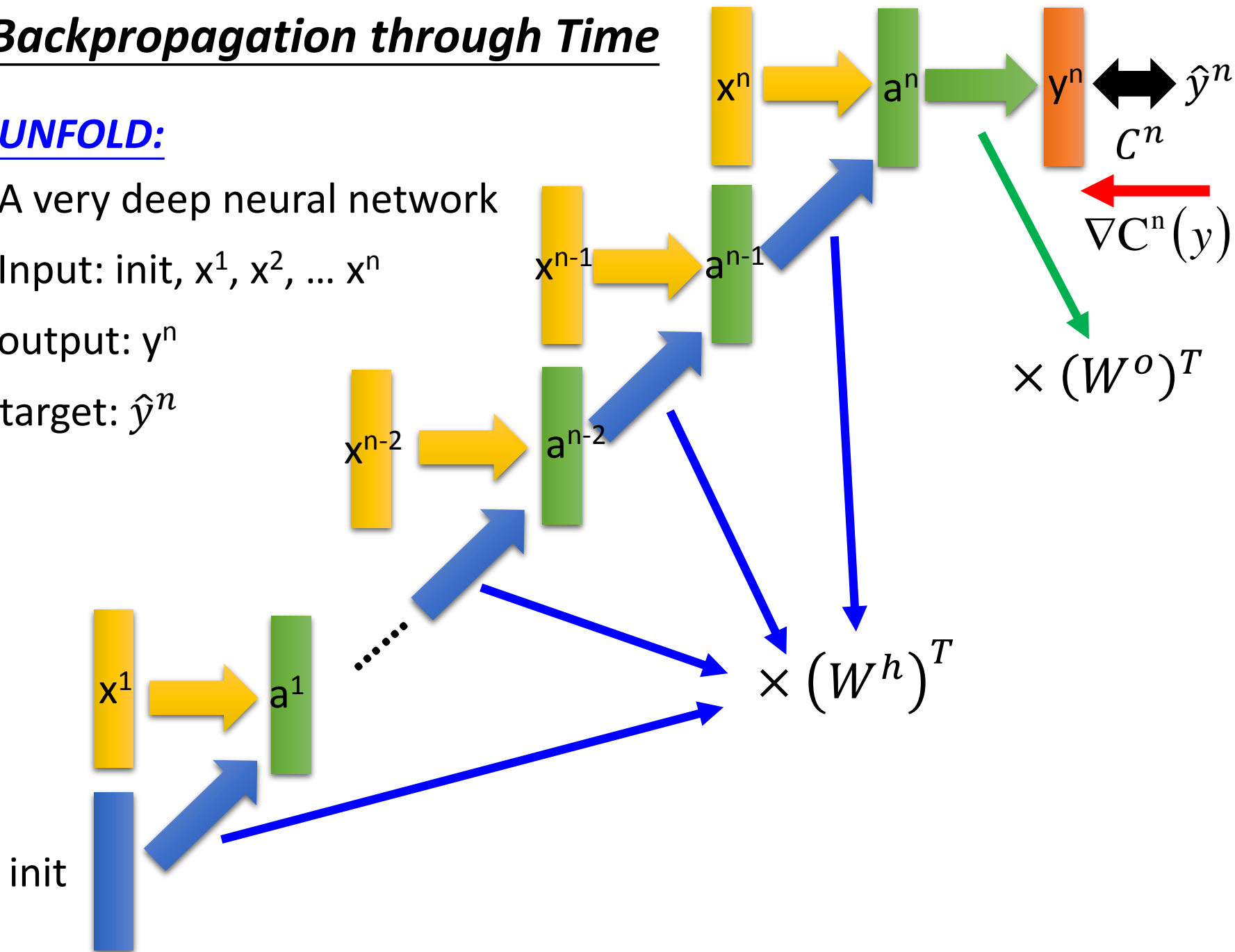
UNFOLD:

A very deep neural network

Input: init, x^1, x^2, \dots, x^n

output: y^n

target: \hat{y}^n



Backpropagation through Time

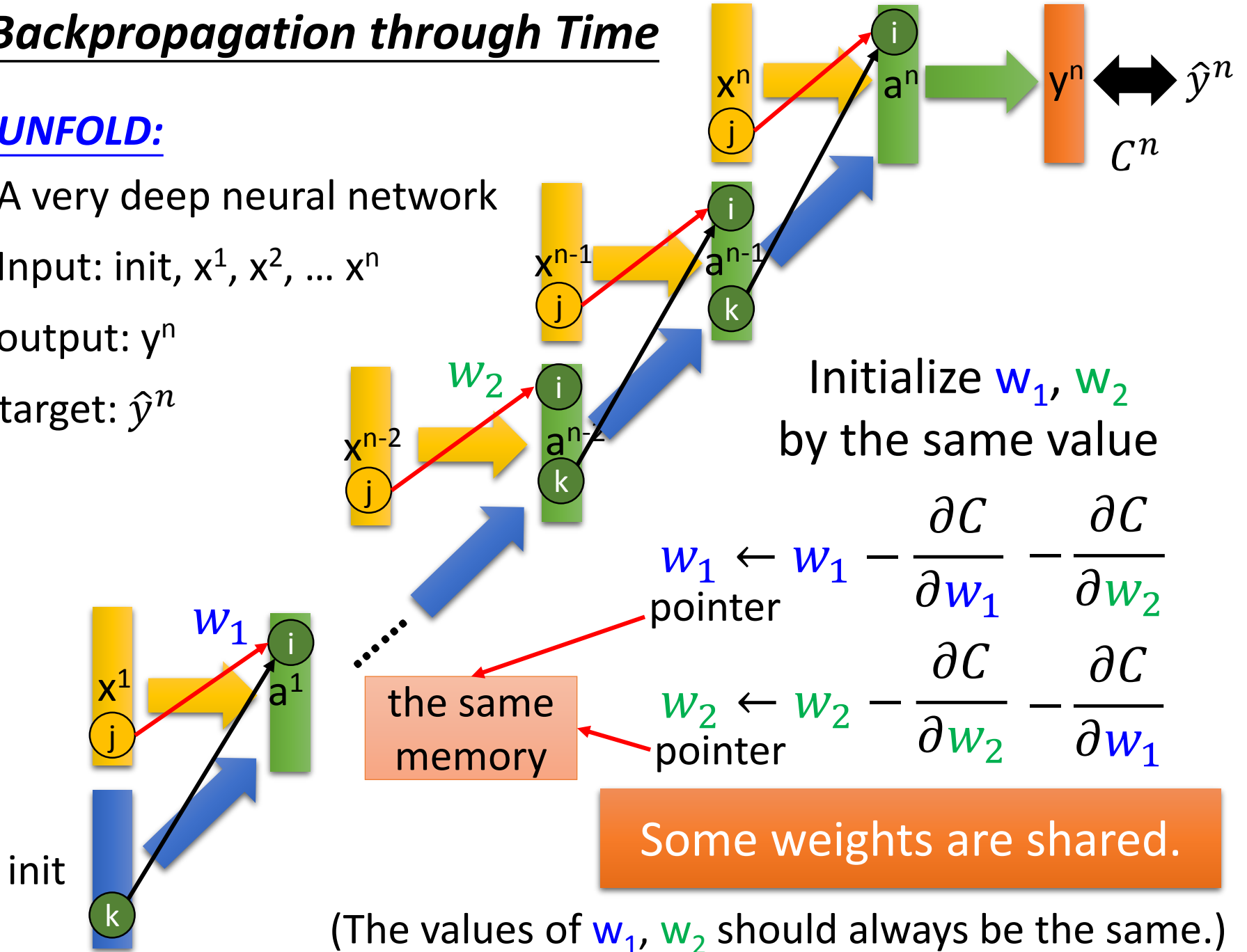
UNFOLD:

A very deep neural network

Input: init, x^1, x^2, \dots, x^n

output: y^n

target: \hat{y}^n



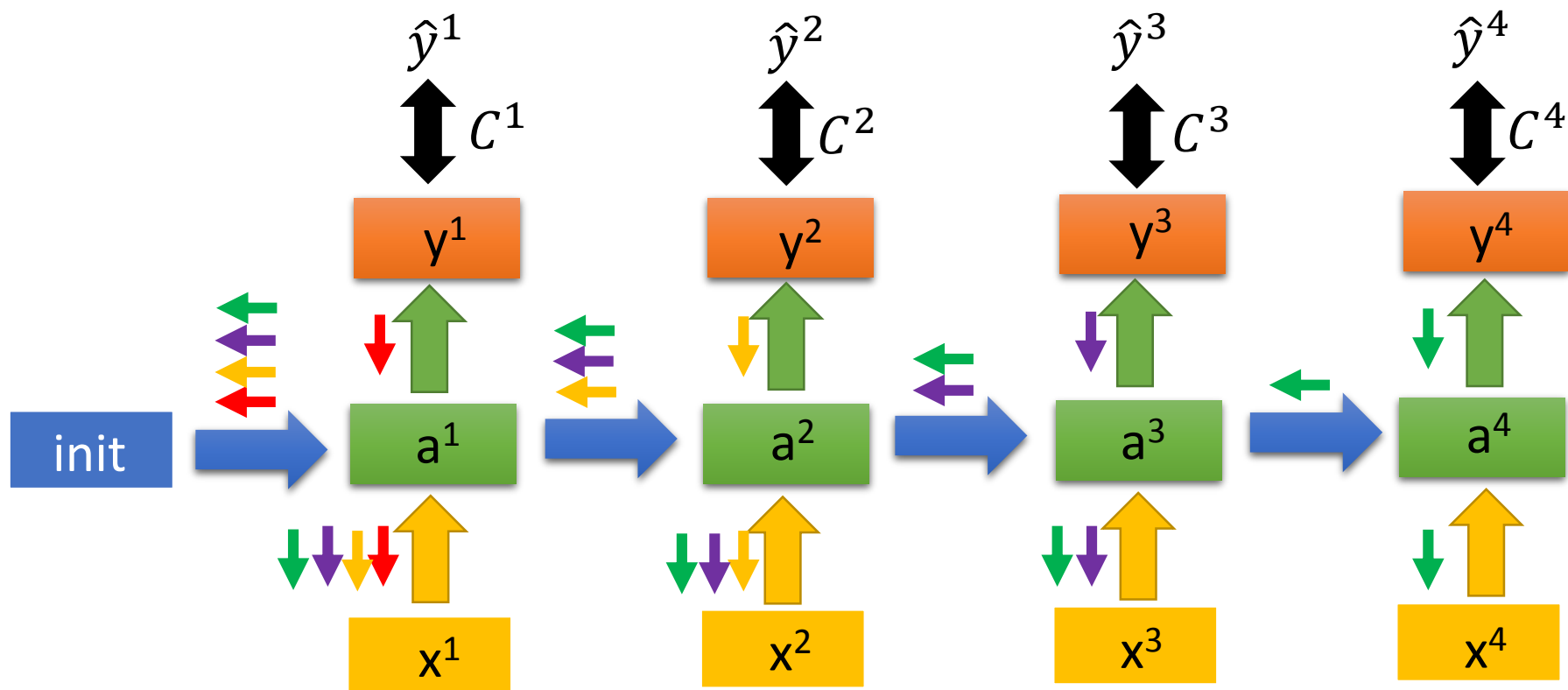
BPTT

Forward
Pass:

Backward
Pass:

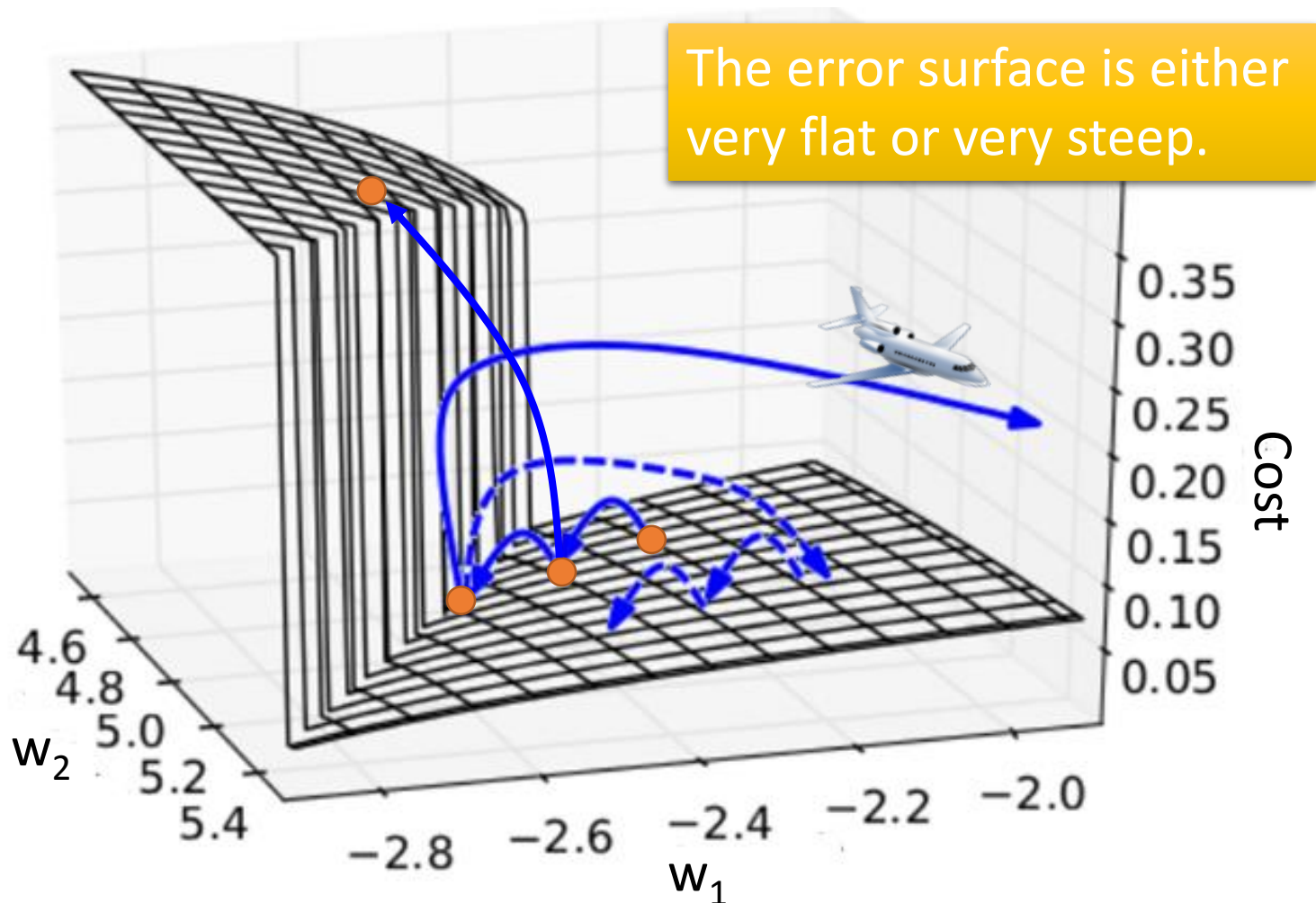
Compute $a^1, a^2, a^3, a^4 \dots$

→ For C^4 → For C^3
→ For C^2 → For C^1



Unfortunately, it is not
easy to train RNN.

The error surface is rough.



Source: <http://jmlr.org/proceedings/papers/v28/pascanu13.pdf>

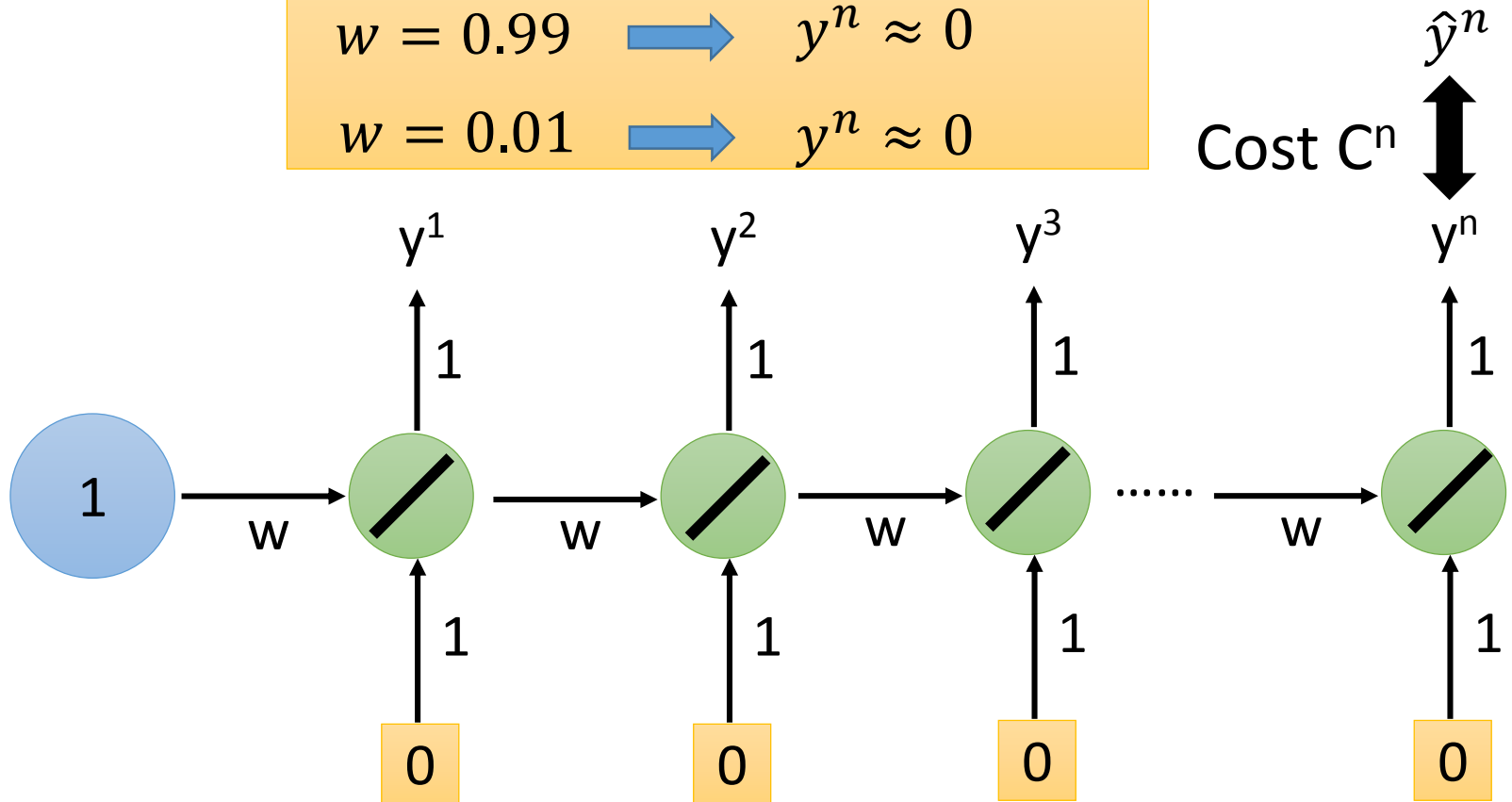
Toy Example

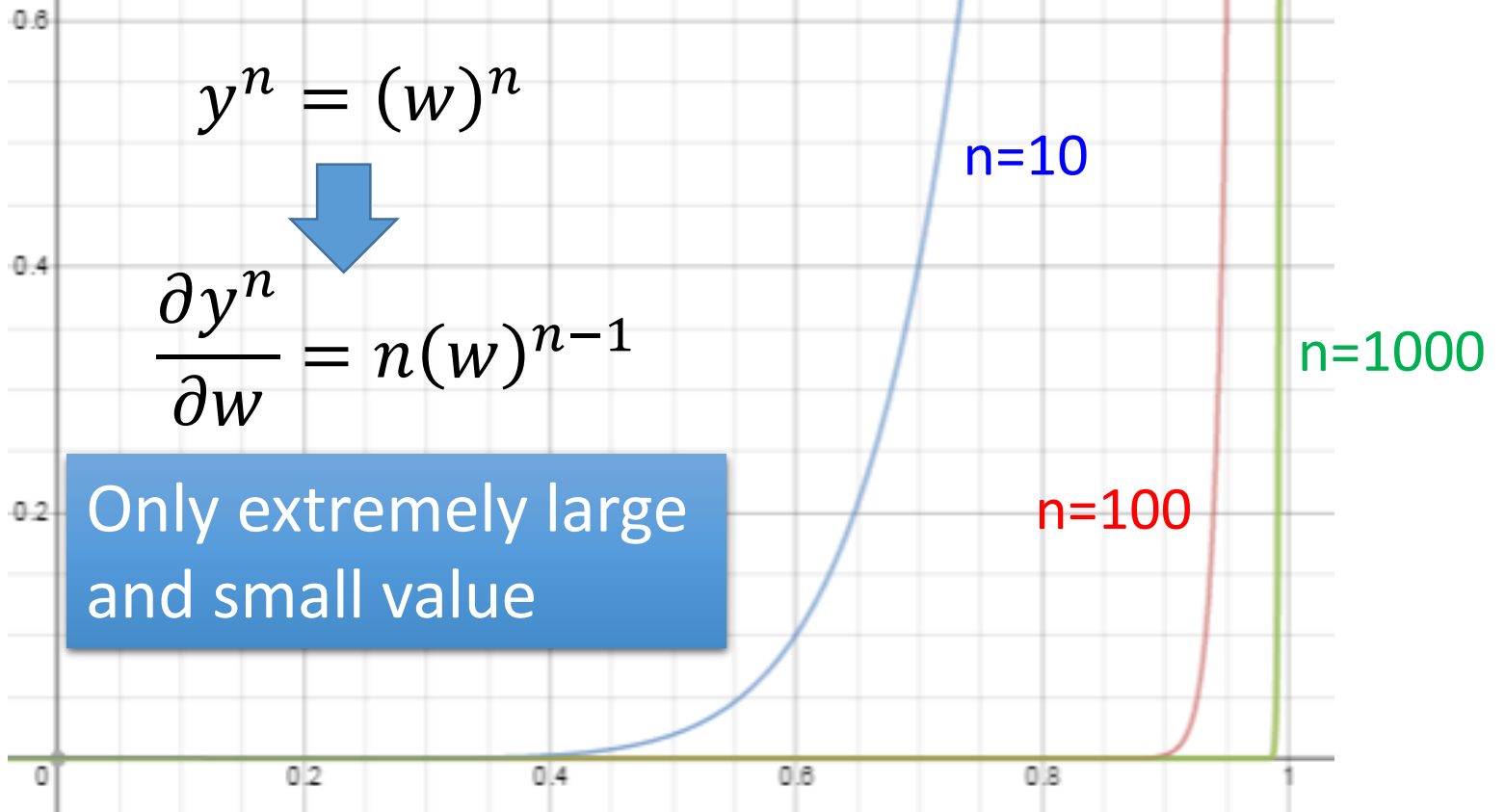
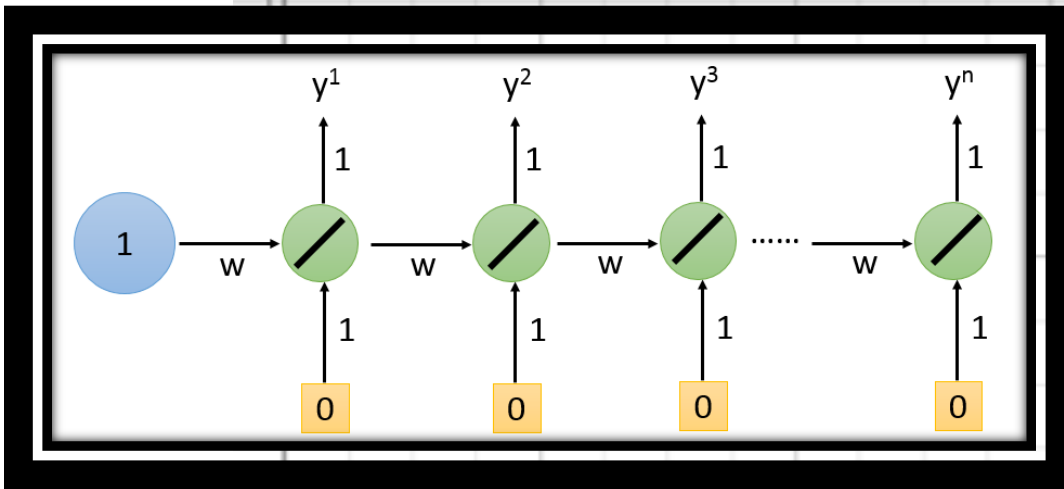
$$\frac{\partial C^n}{\partial w} = \frac{\partial C^n}{\partial y^n} \frac{\partial y^n}{\partial w} \quad \frac{\partial y^n}{\partial w} \approx \frac{\Delta y^n}{\Delta w}$$

If $n = 1000$:

$w = 1 \quad \longrightarrow \quad y^n = 1$
 $w = 1.01 \quad \longrightarrow \quad y^n \approx 20000$

$w = 0.99 \quad \longrightarrow \quad y^n \approx 0$
 $w = 0.01 \quad \longrightarrow \quad y^n \approx 0$

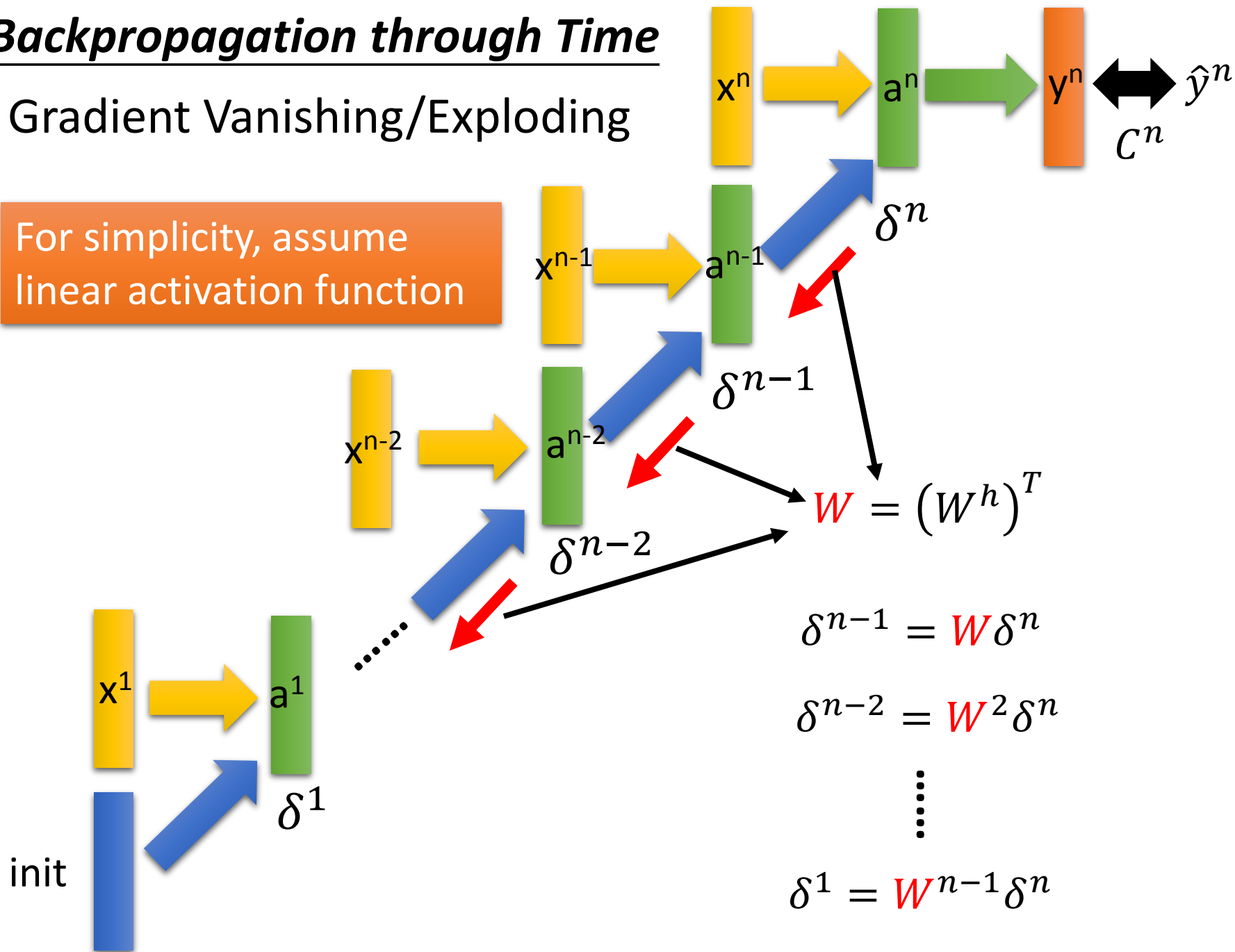




Backpropagation through Time

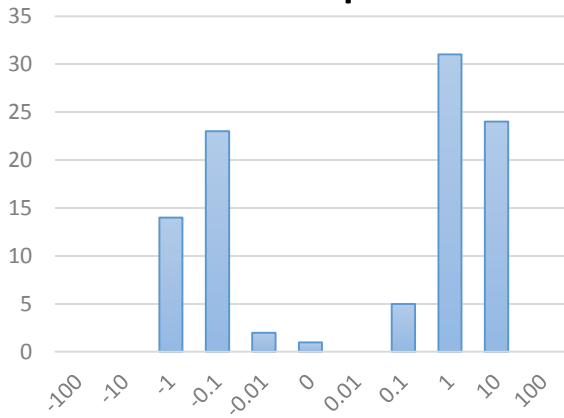
Gradient Vanishing/Exploding

For simplicity, assume linear activation function

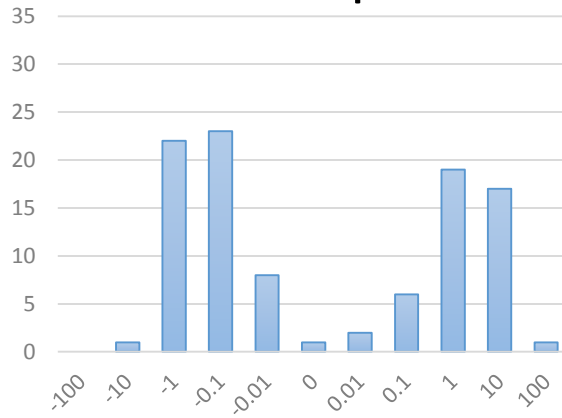


Gradient Vanishing/Exploding

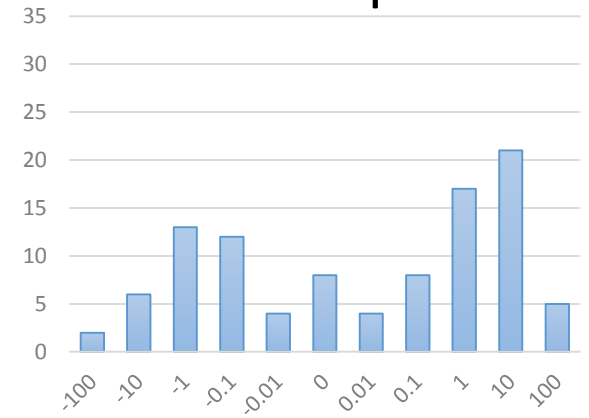
1 step



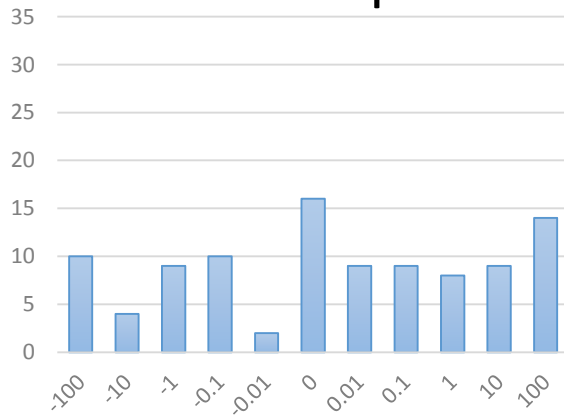
2 step



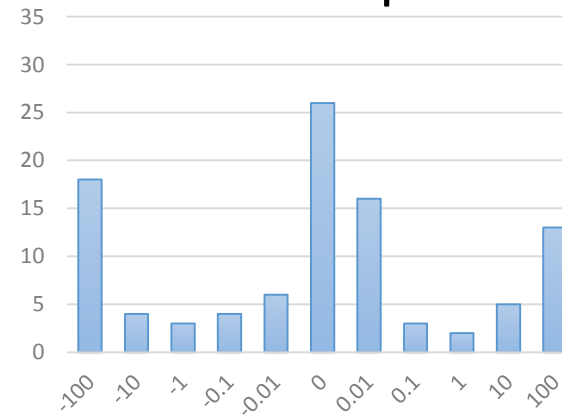
5 step



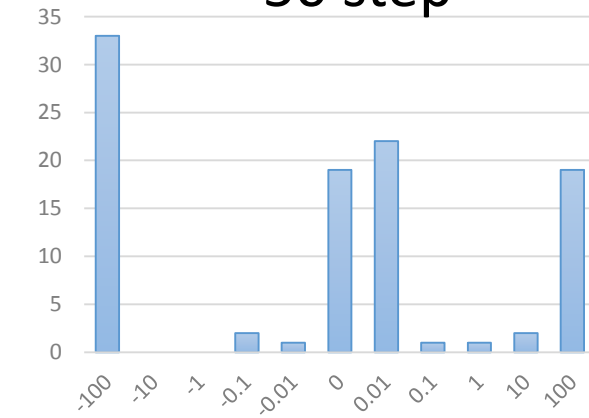
10 step



20 step

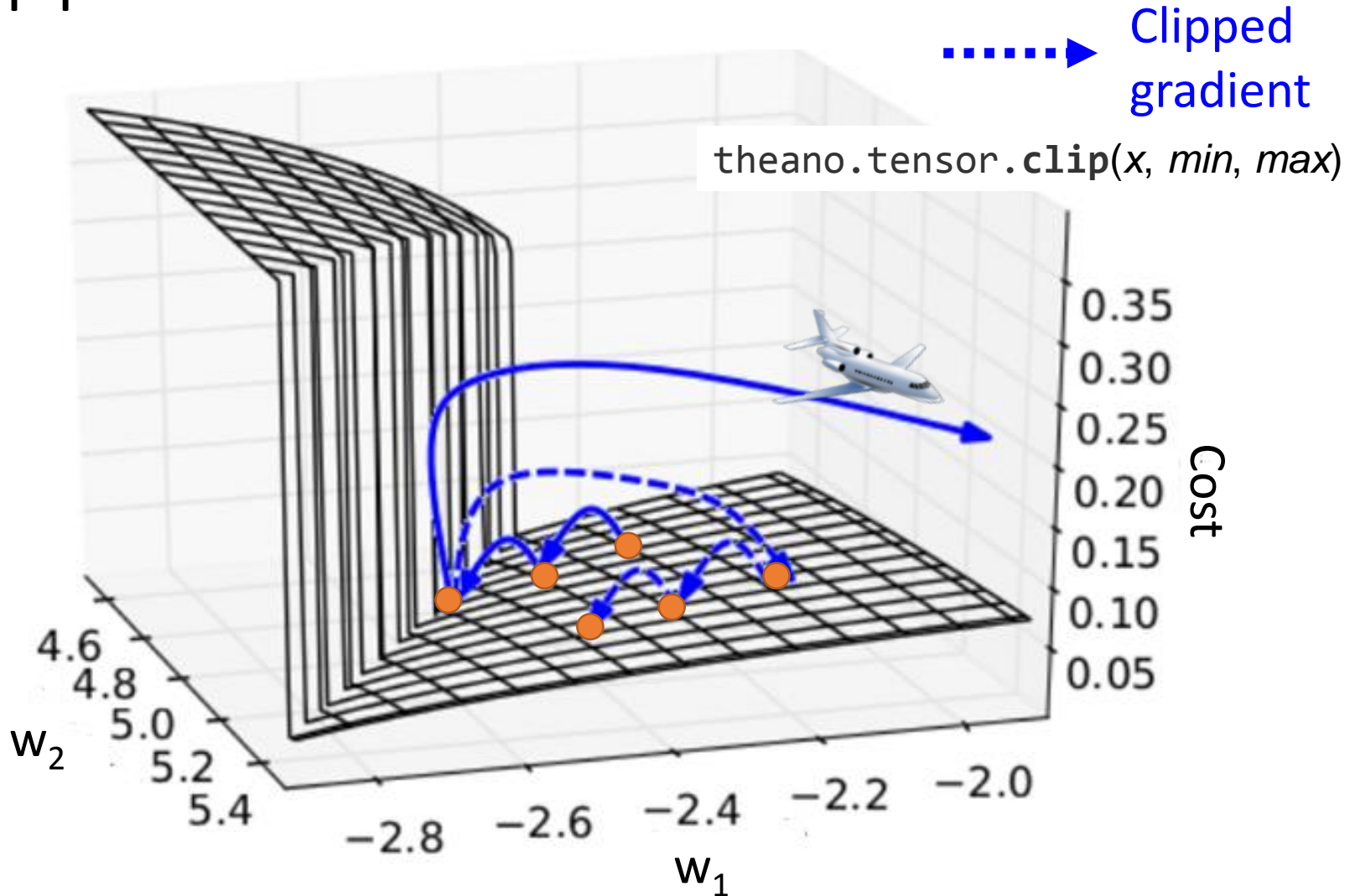


50 step



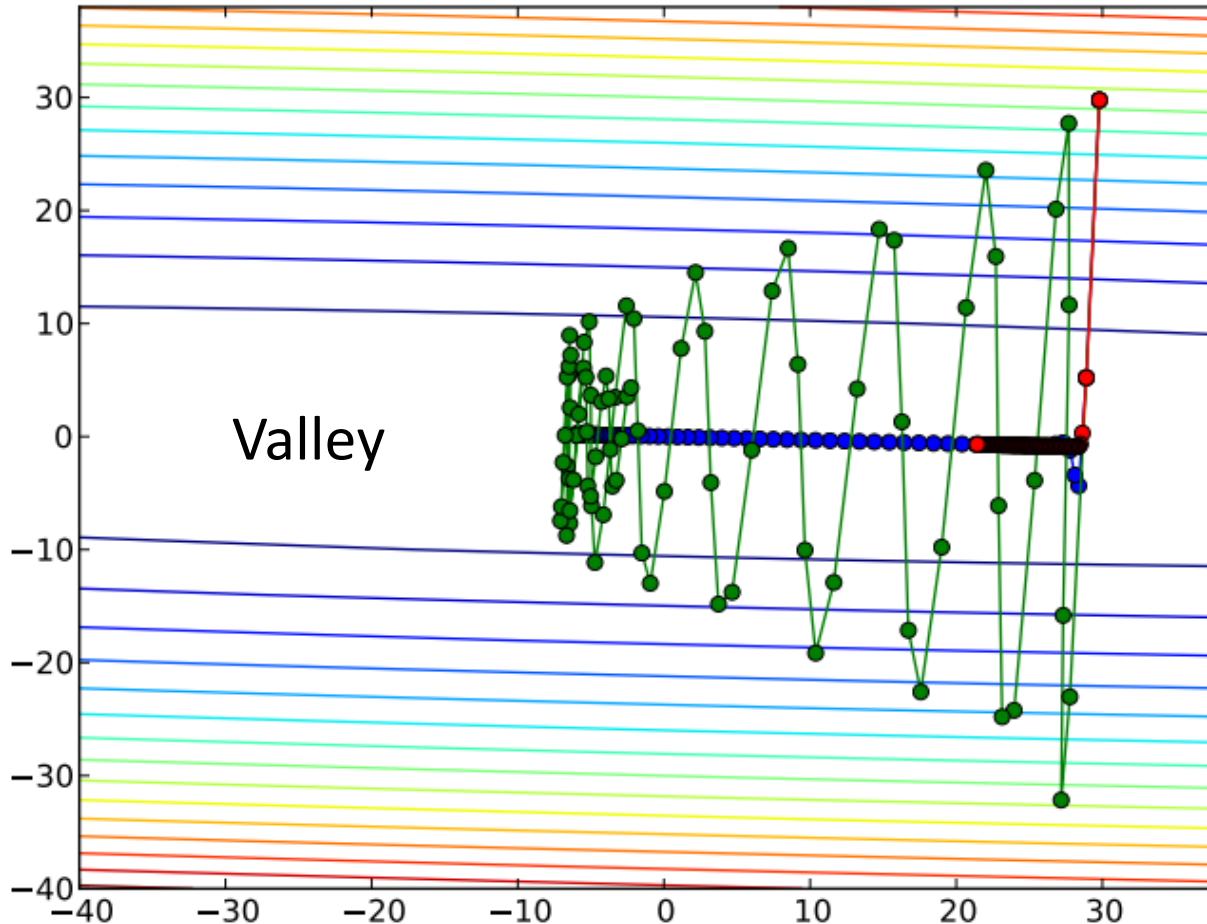
Possible Solutions

Clipped Gradient



Source: <http://jmlr.org/proceedings/papers/v28/pascanu13.pdf>

NAG



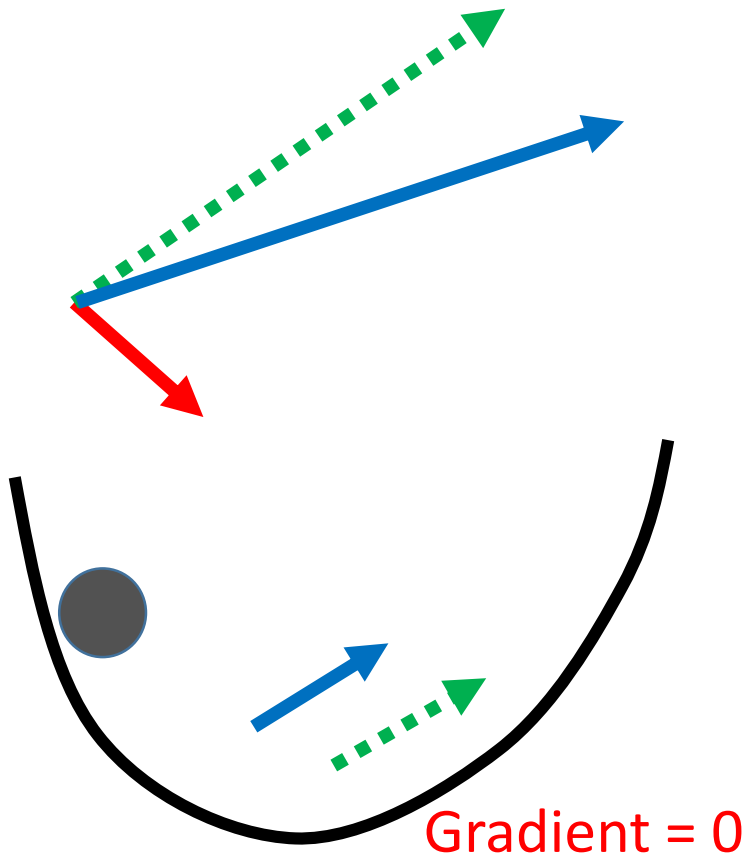
Methods:

- Gradient descent
- Momentum
- Nesterov's Accelerated Gradient (NAG)

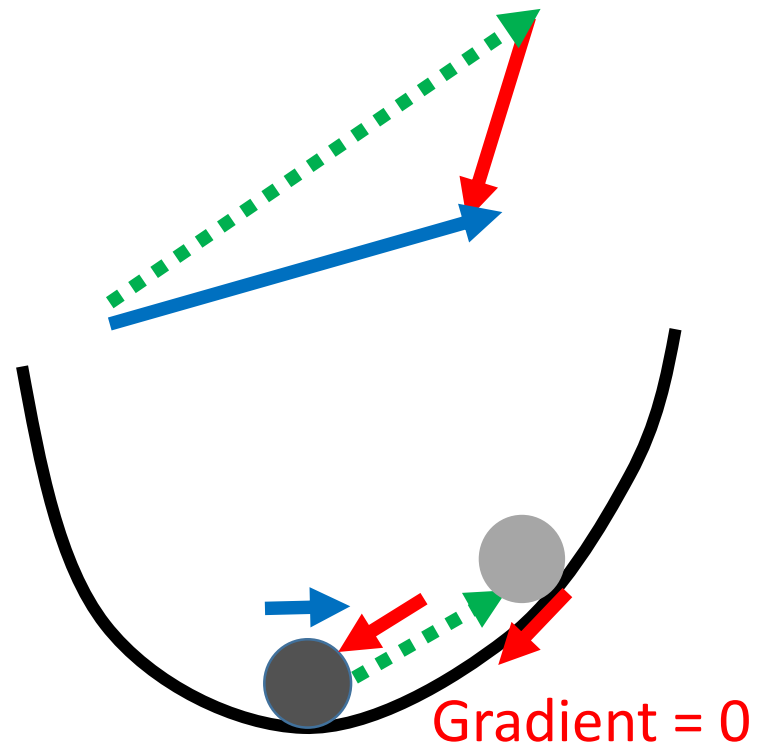
NAG

- Gradient
- Movement
- ⋯→ Last Movement

- Momentum

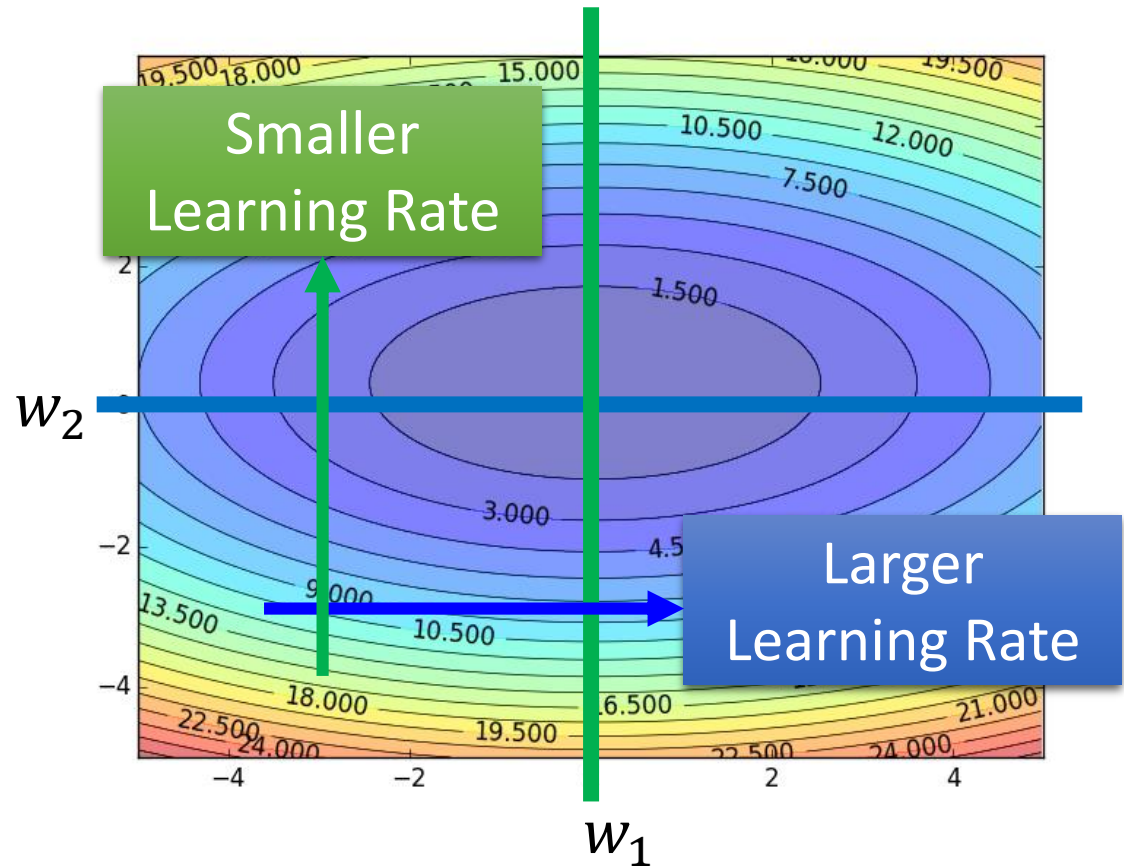


- Nesterov's Accelerated Gradient (NAG)



RMSProp

Review:
Adagrad



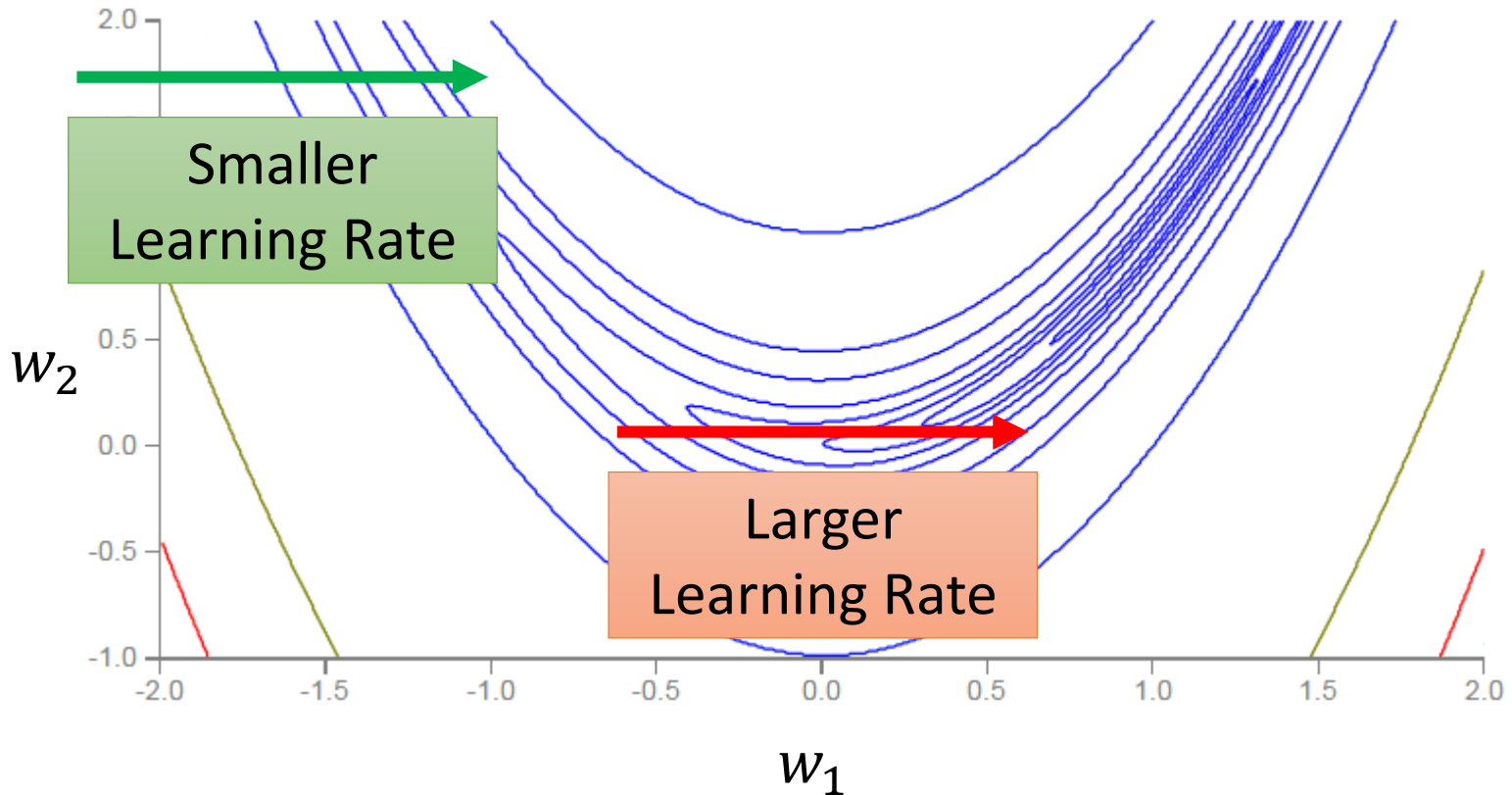
$$w^{t+1} \leftarrow w^t - \frac{\eta}{\sqrt{\sum_{i=0}^t (g^i)^2}} g^t$$

A blue arrow points from the denominator of the fraction to the text box below.

Use first derivative to estimate second derivative

RMSProp

Error Surface can be even more complex when training RNN.



RMSProp

$$w^1 \leftarrow w^0 - \frac{\eta}{\sigma^0} g^0 \quad \sigma^0 = g^0$$

$$w^2 \leftarrow w^1 - \frac{\eta}{\sigma^1} g^1 \quad \sigma^1 = \sqrt{\alpha(\sigma^0)^2 + (1 - \alpha)(g^1)^2}$$

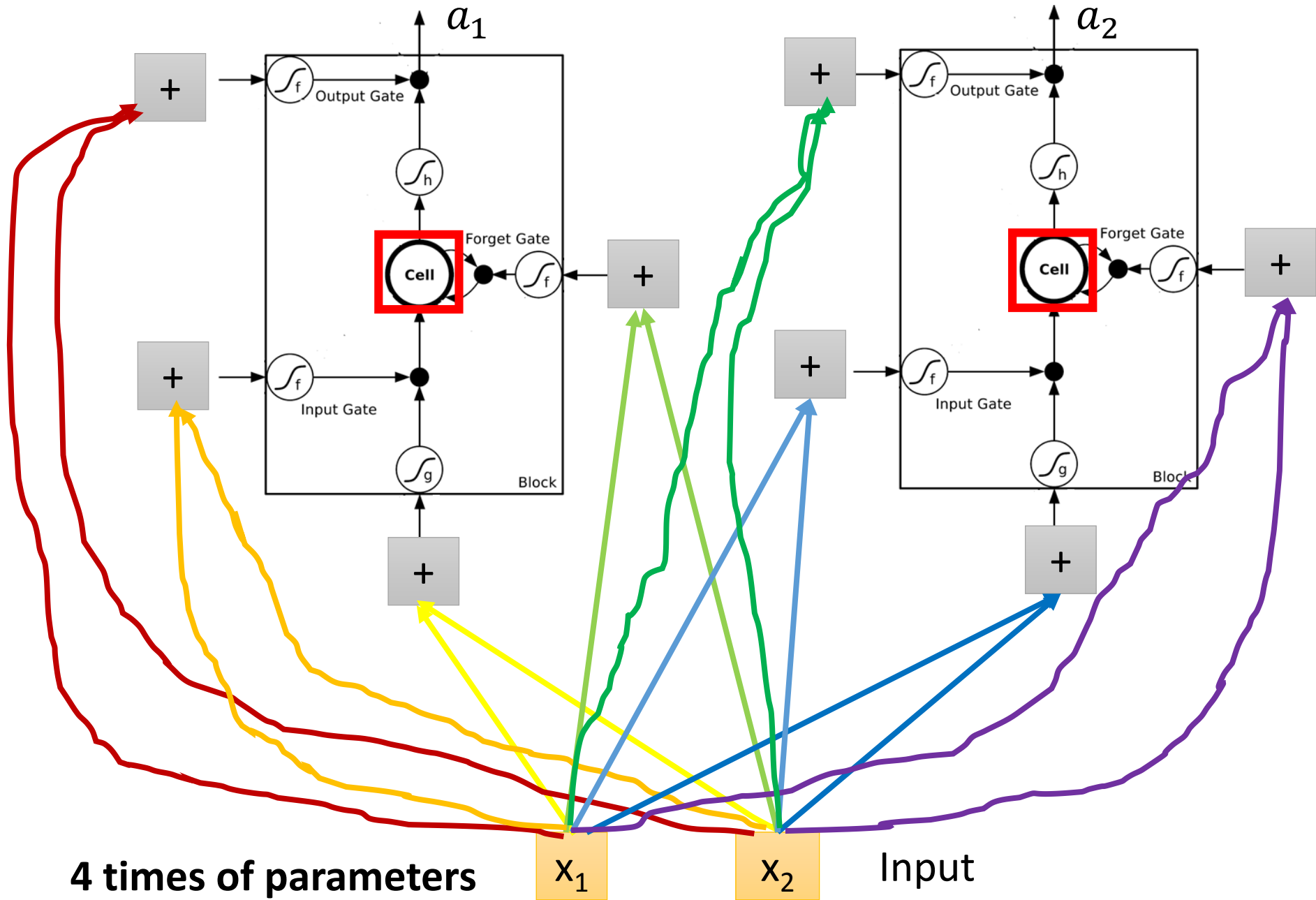
$$w^3 \leftarrow w^2 - \frac{\eta}{\sigma^2} g^2 \quad \sigma^2 = \sqrt{\alpha(\sigma^1)^2 + (1 - \alpha)(g^2)^2}$$

⋮

$$w^{t+1} \leftarrow w^t - \frac{\eta}{\sigma^t} g^t \quad \sigma^t = \sqrt{\alpha(\sigma^{t-1})^2 + (1 - \alpha)(g^t)^2}$$

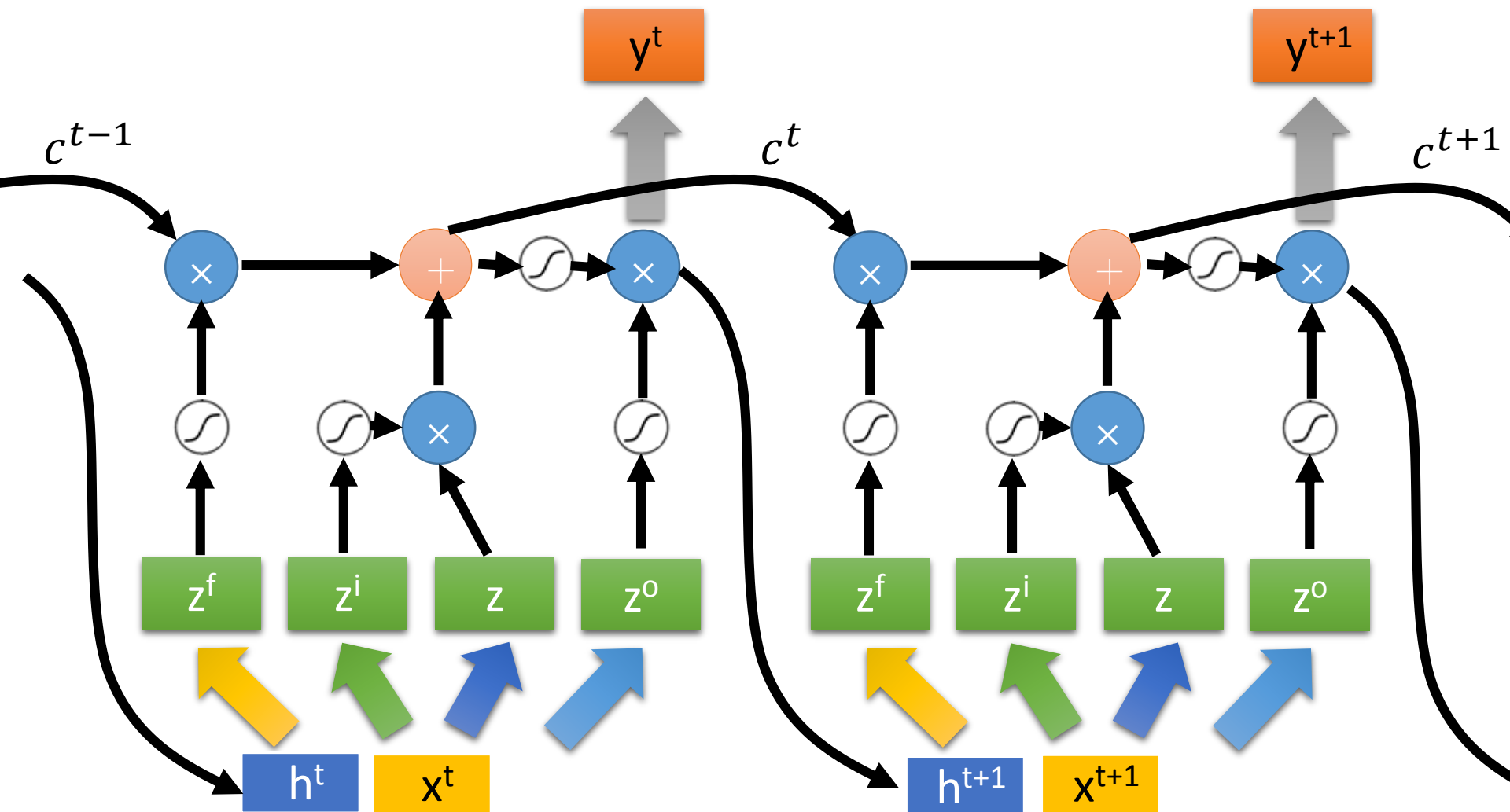
Root Mean Square of the gradients
with previous gradients being decayed

LSTM can address the gradient vanishing problem.

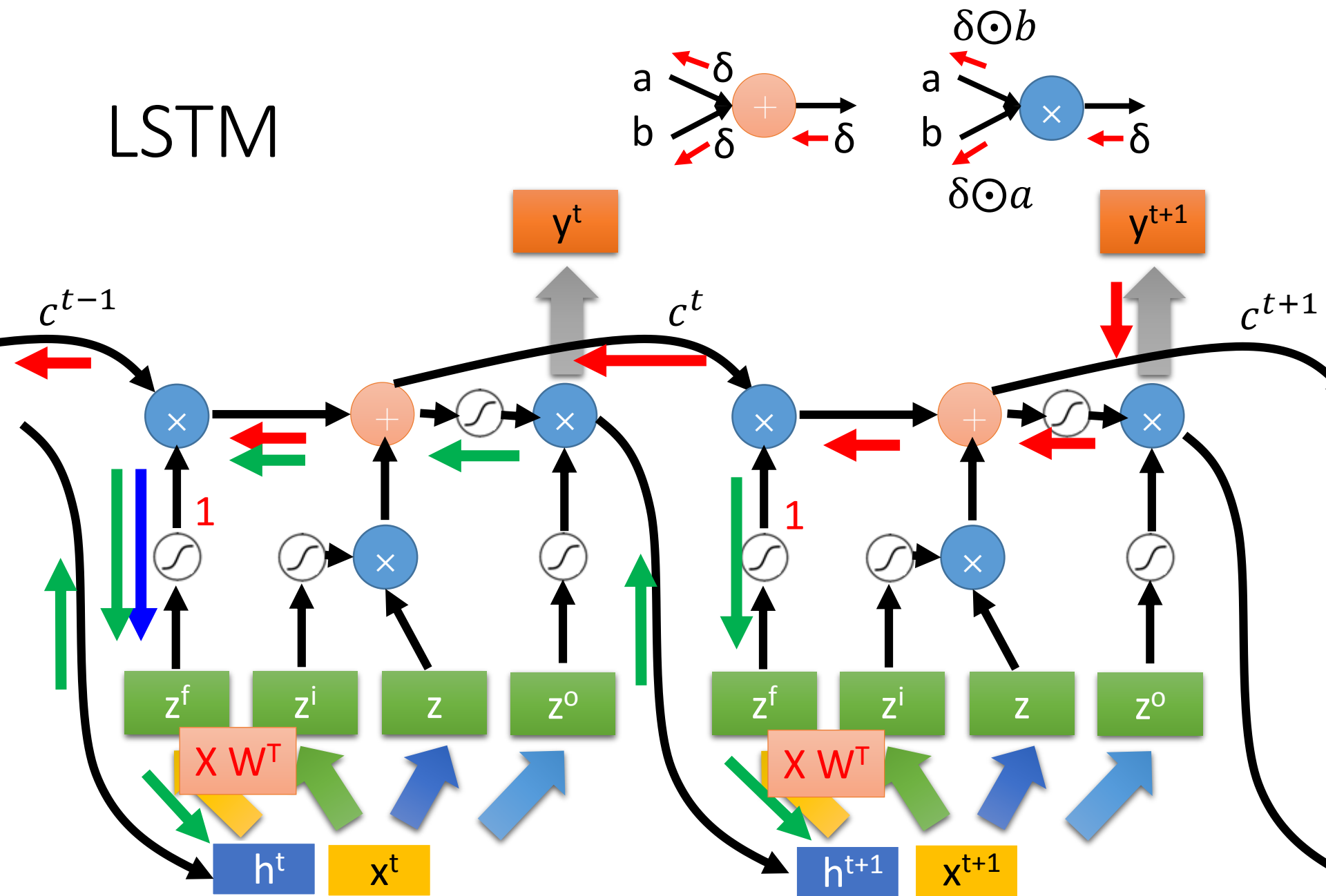


LSTM

Extension: "peephole"

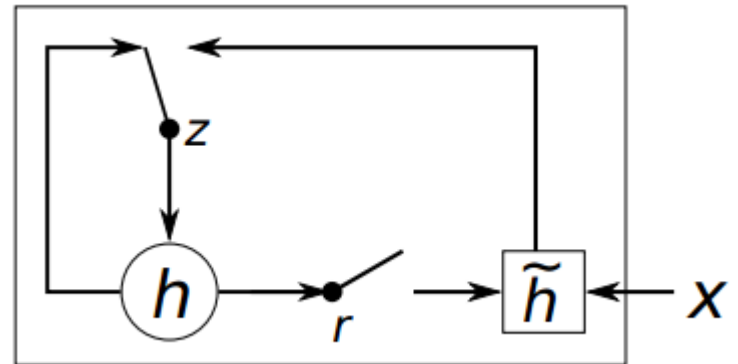


LSTM

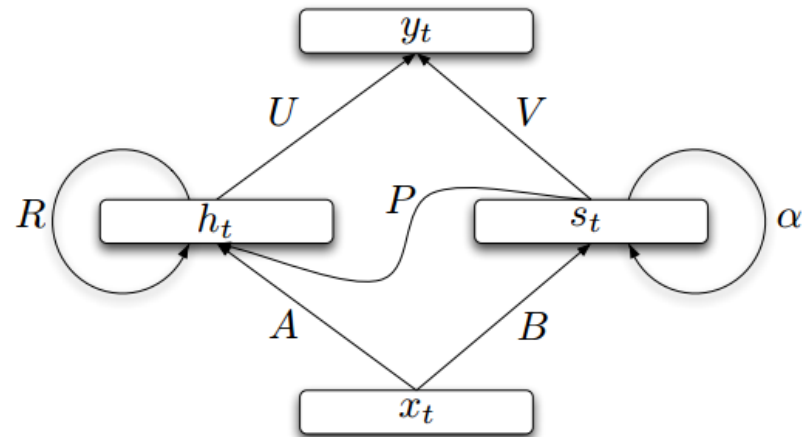


Other Simpler Variants

- GRU: Cho, Kyunghyun, et al. "Learning Phrase Representations using RNN Encoder–Decoder for Statistical Machine Translation", EMNLP, 2014



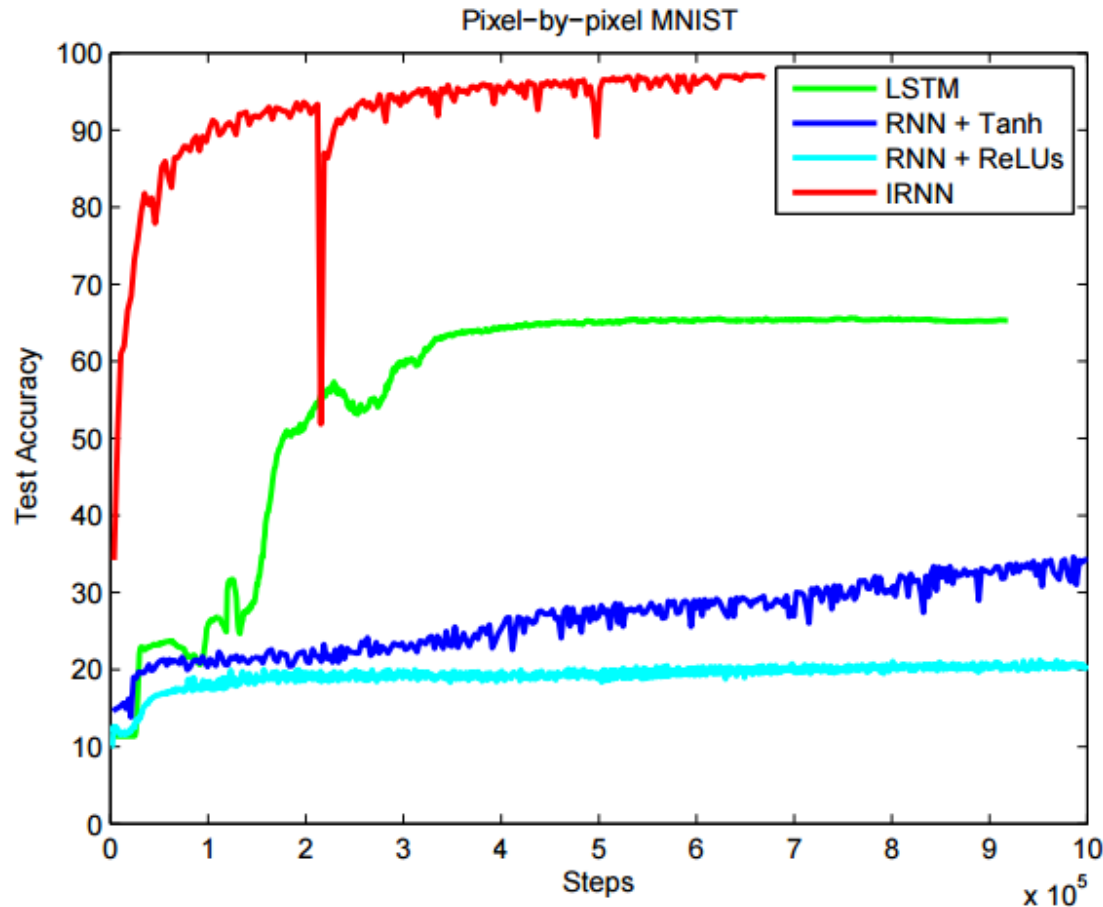
- SCRN: Mikolov, Tomas, et al. "Learning longer memory in recurrent neural networks", ICLR 2015



Better Initialization

Quoc V. Le, Navdeep Jaitly, Geoffrey E. Hinton, "A Simple Way to Initialize Recurrent Networks of Rectified Linear Units", 2015

- Vanilla RNN: Initialized with Identity matrix + ReLU



Concluding Remarks

- Be careful when training RNN ...
- Possible solution:
 - Clipping the gradients
 - Advanced optimization technology
 - NAG
 - RMSprop
 - Try LSTM (or other simpler variants)
 - Better initialization